Single Surface Membrane Optical Shell Technology - Current Status -

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  – “Extremely Lightweight, Segmented Membrane Optical Shell Substrate Technology (MOST) for Future IR to Optical Telescopes”
  – COTR: Dr. Bill Jones, NASA-MSFC, Contract # NNM07AA42C
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• **Colleagues at Mevicon Inc.**
• **Other Projects**
Overview

Membrane Shell Technology

- **Inherent Stiffness**: Derived from curvature
- **Low Areal Density**: Multiple sources
- **Compact Stowage**: Rolling
  - No folding/creasing
  - No discrete hinge mechanisms
- **Deterministic Self Deployment**
- **Zero Energy Self-Rigidization**
- **Scalability**
- **Cost /Schedule Advantages**
  - Thin film based ($\approx 40\text{g/m}^2$ @ 25 µm thick)
  - Single surface
  - Minimal support structure
  - Minimal deployment and rigidization support hardware requirements

**Roll Stow**

**Release to Self Deploy**

**Use**

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Application Areas

Solar
- Power
  - Higher Gain PV
  - Solar Dynamic

RF Aperture
- SATCOMM
- RADAR
- Science
- S-Band to W Band
- THz
- Emergency Use
- Transportable
- Expandable

Optics
- IR
- LIDAR
- LaserComm
- Imaging
- Telescopes
  - Ultra-lightweight
  - Ultra-compact

Solar Sails, MLI, Sunshields, ...

Solar Power
- Higher Gain PV
- Solar Dynamic

Propulsion
- STP/SOTV
- Solar Sails

Terrestrial
- Water
  - Purification
  - Distillation
- Solar Cooking
Strength Through Curvature

0.4 and 0.6 m examples of discrete boundary mounting on lightweight structures
Background: Space Heritage Materials

- **Material Types**
  - Polyimides (Kaptons, ...)
  - Polyesters (Mylars, ...)

- **Space Use Examples**
  - MLI Blankets
  - Sun Shields (Skylab ... JWST)
  - Blanket Type Solar Arrays
  - RF Aperture Shields
  - Flex Circuits

Echo Test Model, ≈1960, LEO, 30 m diameter
Optical Quality Materials

Optical Grade Reflective Films (from left to right 3 to 5 nm rms micro roughness, minimal thickness variation, demonstrated interferometric optical measurements showing 20 nm rms or less surface figure, very promising preliminary optical shop and interferometric test results on powered surfaces)

Demonstrated Optical Level Boundary Control (example from 10 cm flat)
• Shown material/coating combos are the ‘standard’ stocked materials
• Many other materials/coatings demonstrated as well.
Process Compatibility
With Wide Range of Materials & Coatings
Flexible Process
Can Produce Range of Depths

- Variety of prescriptions can be made with the same fixture
- Yields strong cost/schedule advantage
- Shown examples vary in R# from 2.2 to 0.9
Efficient Process

Multiple example 0.2m shells
Current Global Figure Metrics

Prescription
• On-Axis,
• 0.2 m aperture
• ROC = 0.22m (fast)

Figure Error (over 80% diameter)
• 7.6 to 7.8 um rms, 7 to 10x Peak Valley
• 10 um contour settings, boundary corrected
• Dominated by spherical aberration terms
• Noise floor
  - Photogrammetry: About 1-2 um rms
  - Material : About 1-2 um rms
Example Shells: 0.1 m, 0.3 m, and 0.75 m (stowed 0.75 m and coffee mug for scale)

Plans for 1.1 and 2.0 m fabrication hardware in development
Multiple paths exist. Direct formation scalable to 8m with investment in new tooling. Other approaches include segments that are separately formed and then either bonded or separately stowed.

Currently produce shells up to 0.75m diameter

- 0.1m (4")
- 0.3m (12")
- 0.75m (30")
- 1.0 to 1.2m (40 to 48")
- 2.0m (80")
- 3.4m (134")

Upper limit of roll to roll coating facilities.

Next Proposed Fab. Capability

Limit of typical master rolls

Spin casting to 6 to 8m OD allows larger single films

Batch coating process exist to 8+m
Scalable Process: Segmentation

Example 0.5m aperture constructed from 0.2m hexagon segments
Multiple Scaling Paths

• Ever Larger Continuous Surfaces
  – 0.1, 0.3, 0.75 . . . (1.1, 2.0, 3.4, 8.0 m)

• Segments (also ever larger)
  – Individually Stowed/Deployed
    • Rolled
    • Stacked
  – Joined (yields larger)
    • Continuous Surface
    • Larger Segments
1.0m Segmented Prototype

- Segments (0.5m c2c, 0.6m ROC, F/0.6)
- System (1.0m diameter, 0.6m ROC, F/0.3)
Two Segment Prototype Assembly

- Initial Demonstration – Test the basic repeating structure of a single ring (7 hexagons) segmented reflector
- Segmentation requires rigid body adjustment of the outer hexagon to align it with center hexagon
- To save cost, off-the-shelf optical alignment part provides tip-tilt and piston motion of the segment’s center attachment point
  - Currently manual adjustment
  - Three 100 pitch threads
Photogrammetry Tests

- Two segment assembly was placed into Mevicon’s 0.5 m photogrammetry test setup
- Photogrammetry was used to measure point locations on the two hexagons
  - 16 coded targets around the segments
  - Projected dots onto segment’s surface
  - 16 image locations used in processing
- Currently, post-processing point locations to generate surface error plots
Closed Loop Control Test

- Using adjustment screws, aligned side hexagon with center hexagon
- Initial surface error (left) shows tilt and piston error between center and side hexagon
- First adjustment corrects most of the tilt error
- Next two adjustments reduce the piston error between segments
- Reduction in surface rms from 1.4 mm to 832 microns
- Residual error dominated by gravity induced astigmatism

Initial Installation

Test sphere reference, $\phi$ 0.46 m,
Sphere, R 0.284m, R# 0.7m
RMS = 1.4 mm, PV = 9.8 mm
500 $\mu$m Contours, Ri-Ro 0.0%-90.0%

Step 1

Test sphere reference, $\phi$ 0.46 m,
Sphere, R 0.267m, R# 0.6m
RMS = 1.3 mm, PV = 7.2 mm
500 $\mu$m Contours, Ri-Ro 0.0%-90.0%

Step 2

Test sphere reference, $\phi$ 0.46 m,
Sphere, R 0.263m, R# 0.6m
RMS = 990 $\mu$m, PV = 6.2 mm
500 $\mu$m Contours, Ri-Ro 0.0%-90.0%

Step 3

Test sphere reference, $\phi$ 0.46 m,
Sphere, R 0.260m, R# 0.6m
RMS = 832 $\mu$m, PV = 5.5 mm
500 $\mu$m Contours, Ri-Ro 0.0%-90.0%
Example Test Image $\rightarrow$ Point Cloud

$N_{seg} = 7$ Center Mount Pathfinder
Improved N=7 Segmented Two Point Mount Prototype

1 shell and mount removed to enhance clarity
Improved N=7 Segmented Two Point Mount Prototype Rigid Body Alignment Results

Example progression in manual adjustment of rigid body alignment of 2 point mount, 7 segment spherical system. Initial error was decreased by more than a factor of 5 in an rms sense (from 4.1 to 0.788 μm rms).

Test 428_001, ∅ 0.19 m,
Sphere, R 0.278m, R# 2.1m
RMS = 4.1 mm, PV = 52.6 mm

Test 428_005, ∅ 0.19 m,
Sphere, R 0.287m, R# 2.2m
RMS = 1.0 mm, PV = 7.1 mm

Test 428_010, ∅ 0.19 m,
Sphere, R 0.288m, R# 2.2m
RMS = 818 μm, PV = 8.6 mm

Test 428_013, ∅ 0.19 m,
Sphere, R 0.287m, R# 2.2m
RMS = 788 μm, PV = 7.2 mm

500 μm Contours, Ri-Ro 0.0%-70.0%
500 μm Contours, Ri-Ro 0.0%-70.0%
500 μm Contours, Ri-Ro 0.0%-70.0%
500 μm Contours, Ri-Ro 0.0%-70.0%
N=19 Segmented Prototype
N=19 Segmented Prototype
N=19 Segmented Prototype Backside
Optical Grade Reflective Films (from left to right 3 to 5 nm rms micro roughness, minimal thickness variation, demonstrated interferometric optical measurements showing 20 nm rms or less surface figure, very promising preliminary optical shop and interferometric test results on powered surfaces)

Demonstrated Optical Level Boundary Control (example from 10 cm flat)
Optical Boundary Control

- 5 to 10x Improvement in Experimental Figure Error of 100mm tensioned flat
  - 900 nm → 80 nm at 80mm Aperture
  - 100 nm → 20 nm at 25mm Aperture
- Control Authority Approaching Material Thickness Variation
Very Recent Interferometric Measurement of Spherical Surfaces

Interferometric measurement of a thin-film spherical surface
Pressurized, Tensioned Flat
Diameter: 100 mm
Radius of Curvature: 730 mm
R/7.3, F/3.6
Active Boundary Control

- Fully automated control
- 0.2 m aperture, R# 0.75
- 3 to 4 μm rms repeatedly achieved over 75 to 80% of diameter
- Results primarily limited by coating, fabrication, and material noise floors

As Installed

Test 009_026, $\Theta$ 0.2 m,
RMS = 18.5 μm, R 0.148683 m, R# 0.74
λ 20 μm, Ri-Ro 20%-85%, Pitch 6.5 mm

Post Correction

Test 009_028, $\Theta$ 0.2 m,
RMS = 4.4 μm, R 0.148701 m, R# 0.74
λ 20 μm, Ri-Ro 20%-85%, Pitch 6.5 mm
• Demonstrated ability to enforce Zernike mode shapes on shell via boundary control proves ability to reject Zernike error components of an aberrated shell

• Experimentally, 1 to 2 iteration actuation steps used to approach numerically predicted best match to ideal coefficient shape

• 85% of shell diameter used for fitting and actuator prescription calculation

Experimental Data, 1 Contour = 400 µm

Demo’d authority (±2 mm-surface) = 16,000 waves (P-V-wavefront) at λ = 500 nm

Tip/Tilt (Z11)  Astigmatism (Z22)  Trefoil (Z33)  Tetrafoil (Z44)
Upcoming Steps

- Basic Membrane Shell Technology
  - Continue to scale demonstrated apertures
    - Larger Single Surface Shells (1.1, 2.0m, …)
    - Segmentation (0.5m segments, R=1, R=2, …)
  - Continue to improve shell global figure
  - Address thermal/CTE concerns
    - Material selection
    - Shielding
    - Control
  - Readiness for Flight

- System Demo’s (with Partners)
  - Lightweight primary optics
  - Full Telescope/OTA
    - Incoherent LIDAR
    - Far IR
    - …
    - Optical Imaging (Someday)
  - Environmental

- Transition to Field/Mission Use
- Adaptive Optics
Structural Dynamics
Structural Dynamics
Analytical Fundamental Behavior

From Blevins, …

$$\omega_{i,j} = \sqrt{\frac{E}{\rho} \left[ \frac{\lambda_{ij}^4}{12(1-\nu^2)} \frac{t^2}{r^4} + \left( \frac{1}{R^2} \right) \right]} \rightarrow \frac{1}{R} \sqrt{\frac{E}{\rho}}$$

Implications:

– Plate terms become insignificant if:
  • Material thickness, $t$, is small and/or
  • Reflector aperture radius, $r$, is large

– Modal density
  • ‘DC’ bias (they start high)
  • Closely spaced “plate” modes (thereafter)

– Ideal NNS’s are dynamically stiff ($F/0.5$)
  • 0.5 m diameter = 600 Hz
  • 1.0 m = 300 Hz
  • 10.0 m = 30 Hz
Structural Dynamics
Analytical Fundamental Behavior

Frequency (Hz)

Diameter (m)

0.2m = 1500 Hz
0.5m = 600 Hz
1.0m = 300 Hz
10.0m = 30 Hz

F# 0.25
F# 0.5
F# 0.75
F# 1
F# 1.5
F# 2
Plate Mode
Effects of Edge Discretization on Fundamental Dynamics Can be Readily Alleviated Through More Mounts or Increased Flange Thickness/Stiffness